

# Eigenvalues & Eigenvectors

## 2.1 Agenda Items

- *Eigenvalues (evs) and Eigenvectors (EVs) of a matrix.*
- *Meaning of evs and EVs.*
- *Diagonalizable matrices and similar transformations.*
- *Analytical (pen-paper) method of finding evs.*
- *computational method of finding evs of a matrix (power method, etc).*

**Definition 8** (evs and EVs). Let  $A \in \mathbf{M}_{n \times n}(\mathbb{F})$ , where  $\mathbb{F} = \mathbb{R}$  or  $\mathbb{F} = \mathbb{C}$ . A nonzero vector  $x \in \mathbb{F}^n$  is an EV of  $A$  if  $Ax = \lambda x$  for some  $\lambda \in \mathbb{F}$ .  $\lambda$  is said to be an ev  $A$  corresponding to the EV  $x$ .

## 2.2 Meaning of the equation $AX = \lambda x$

### 2.2.1 Algebraic meaning

$Ax = \lambda x$  can also be written as  $(A - \lambda I)x = 0$ , i.e.,  $\ker(A - \lambda I) = \text{EVs} \sqcup \{0\}$ . In the above equation we use that  $\lambda \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$ . The subspace  $\ker(A - \lambda I)$  has a special name, EIGENSPACE of  $\lambda$  w.r.t.  $A$ .

Consider an example:  $A = \begin{pmatrix} 2 & -1 \\ 2 & 4 \end{pmatrix}$  so that  $A - \lambda I = \begin{pmatrix} 2 - \lambda & -1 \\ 2 & 4 - \lambda \end{pmatrix}$ . Now solving  $Ax = \lambda x$  is equivalent to solving the system of linear equations  $\begin{pmatrix} 2 - \lambda & -1 \\ 2 & 4 - \lambda \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ . This implies that

$$\begin{aligned} (2 - \lambda)x_1 - x_2 &= 0 \\ 2x_1 + (4 - \lambda)x_2 &= 0 \end{aligned}$$

Since EV cannot be 0, finding Evs of  $A$  boils down to the following question:

When does this system of linear equations have a nontrivial solution?

To answer the above question we need to know various features of an invertible matrices:

Let  $B \in \mathbf{M}_{n \times n}(\mathbb{F})$ , where  $F = \mathbb{R}$  or  $\mathbb{C}$ . TFAE

- $B$  is invertible.
- $Bx = b$  has a unique solution in  $\mathbb{F}^n$  for all  $b \in \mathbb{F}^n$ .
- $\text{rref}(B) = I_n$ .
- $\text{rank}(B) = n$ .
- $\text{im}(B) = \mathbb{F}^n$ .
- $\ker(B) = \{0\}$ .

Let us try to answer the above question now. In view of the above equivalence

$$\begin{aligned} \ker(A - \lambda I) \neq \{0\} &\iff (A - \lambda I) \text{ is not invertible} \\ &\iff \det(A - \lambda I) = 0. \end{aligned}$$

In our problem

$$\det(A - \lambda I) = \det \begin{pmatrix} 2 - \lambda & -1 \\ 2 & 4 - \lambda \end{pmatrix} = (2 - \lambda)(4 - \lambda) + 2 = \lambda^2 - 6\lambda + 10$$

The above polynomial in  $\lambda$  is called the *characteristic polynomial for the matrix A*.  
Thus

$$\det(A - \lambda I) = 0 \iff \lambda = 3 \pm i$$

Let us call  $\lambda_1 = 3 + i$  and  $\lambda_2 = 3 - i$ .

To find EV w.r.t.  $\lambda_1$  solve  $Ax = \lambda_1 x$ . After solving we obtain  $(1+i)x_1 + x_2 = 0$ , i.e.,  $x_2 = -(1+i)x_1$ . We can take  $x_1$  to be any nonzero scalar of  $\mathbb{F}$ , say  $k$ , so as to write  $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} k \\ -(1+i)k \end{pmatrix} = k \begin{pmatrix} 1 \\ -1-i \end{pmatrix}$ . Hence any nonzero multiple of the vector  $\begin{pmatrix} 1 \\ -1-i \end{pmatrix}$  is an EV of the matrix  $A$  w.r.t the ev  $\lambda_1$ . Similarly one can find EV corresponding to the ev  $\lambda_2$ .

## 2.3 A Slight Digression

Let  $B \in \mathbf{M}_{n \times n}(\mathbb{F})$ , where  $\mathbb{F} = \mathbb{R}$  or  $\mathbb{F} = \mathbb{C}$ .

*Question:* Why  $\text{null}(B) = \{0\} \iff B$  is invertible ?

*Answer:* For finite dimensional vector spaces  $U, V$  over  $\mathbb{F}$ , a linear transformation  $T : U \rightarrow V$  is invertible if and only if  $T$  is one to one and onto.

*Rank Nullity Theorem:*

$$\text{nullity}(T) + \text{rank}(T) = \dim(U).$$

Since  $T$  is one to one  $\ker(T) = \{0\}$ , i.e.,  $\text{nullity}(T) = 0$ . Also since  $T$  is onto,  $\text{rank}(T) = \dim(V)$ . Therefore by Rank nullity theorem we obtain

$$T \text{ is an isomorphism} \implies \dim(U) = \dim(V).$$

## 2.4 HW/Exercise problem

Q. Consider  $A = \begin{pmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 0 \end{pmatrix}$

1. Find the characteristic polynomial for  $A$ .

2. Find the evs of  $A$ .

3. Find the EVs of  $A$

*Ans:*

$$\begin{aligned} \text{evs: } & -1, 2, 3. \\ \text{EVs: } & \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}. \end{aligned}$$

*Geometrical meaning of  $Ax = \lambda x$ , when  $\lambda$  is real.  $Ax$  is parallel to  $x$ , i.e., the “EV”  $x$  either gets stretched longitudinally when acted upon by the matrix  $A$ .*

## 2.5 Coming Soon!

- *Diagonalizable matrix*
- *Similarity transformation*
- *Application of evs and EVs in solution to ODE*