

5/1/2022

# Agenda items

- \* Diagonalization of matrices
- \* Similarity transformation
- \* Spectral decomposition of matrices

## Last Lecture

- evs & EVs (def<sup>n</sup>, meaning, etc)
- trace of a matrix & its rel<sup>n</sup> w/ evs; det  $\leftrightarrow$  evs.

# Diagonalizable matrices

Certain forms of matrices are convenient to work with . . . .

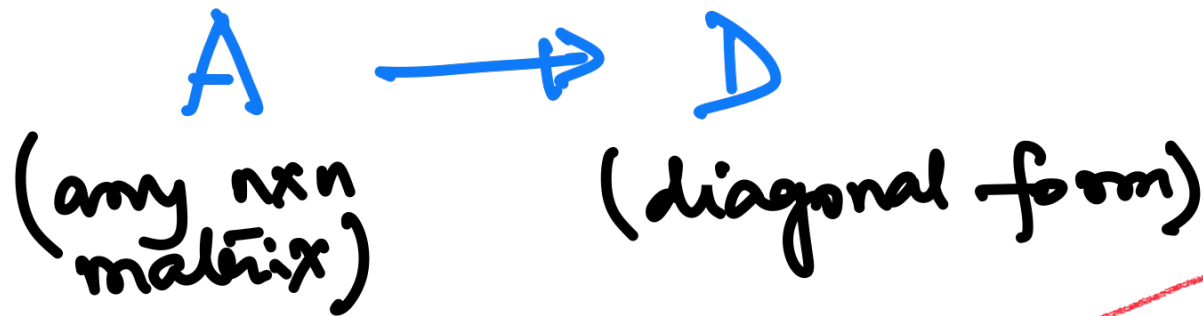
→ Upper/lower triangular forms  
Why?

→ Diagonal forms  
Why?

think LUs,  
think computing powers of matrices, . . .

# Diagonalizable matrices . . .

wouldn't it be nice if



the evs of  $A$  and  $D$  will be same.

$A \in M_{n \times n}(\mathbb{F})$  is diagonalizable over  $\mathbb{F}$  if there exists an invertible matrix  $S$  over  $\mathbb{F}$  s.t.  $A = SDS^{-1}$  or equivalently  $D = S^{-1}AS$  ← similarity transformation

Q) When is a matrix diagonalizable?

Ans)  $A \in M_{n \times n}(\mathbb{F})$  is diagonalizable  
if and only if  $A$  has  $n$   
linearly independent EVs in  $\mathbb{F}^n$

\* An  $n \times n$  complex matrix that  
has  $n$  distinct EVs is diagonalizable.

## Example:

Q) Find a matrix that diagonalizes

$$A = \begin{pmatrix} 2 & -1 \\ 2 & 4 \end{pmatrix}$$

Ans Solve  $|A - \lambda I| = 0$  to obtain

$$\lambda_{1,2} = 3 \pm i$$

then use  $A\vec{x}_j = \lambda_j \vec{x}_j$ ;  $j=1,2$

$$\vec{x}_1 = \begin{pmatrix} \frac{-1+i}{2} \\ 1 \end{pmatrix}; \vec{x}_2 = \begin{pmatrix} \frac{-1-i}{2} \\ 1 \end{pmatrix}$$

to obtain  $S = \begin{pmatrix} \frac{-1+i}{2} & \frac{-1-i}{2} \\ 1 & 1 \end{pmatrix}$  diagonalizes  $A$ .

check if  $S^{-1}AS$  is  $D$ ?


$$\begin{aligned}
 S^{-1}AS &= \begin{pmatrix} -i & \frac{1-i}{2} \\ +i & \frac{1+i}{2} \end{pmatrix} \begin{pmatrix} 2 & -1 \\ 2 & 4 \end{pmatrix} \begin{pmatrix} \frac{-1+i}{2} & \frac{-1-i}{2} \\ 1 & 1 \end{pmatrix} \\
 &= \begin{pmatrix} 3+i & 0 \\ 0 & 3-i \end{pmatrix} \\
 &= D!
 \end{aligned}$$

~~\*~~ the Col<sup>m</sup> vectors of  $S$  form an eigenbasis for  $A$  & the diagonal entries of  $D$  are the associated eVs.

Ques) What are the evs and EVs  
of the  $n \times n$  identity matrix  
 $\mathbb{I}_n$ ?

Is there an eigenbasis for  $\mathbb{I}_n$ ?

Which matrix diagonalizes  $\mathbb{I}_n$ ?

 This is in some sense a silly & yet-  
a conceptually trick question !!

## Example

Q) Find the eigenspace of  $A = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ .

Is  $A$  diagonalizable?





Ans the evs are along the diagonal.

$$\lambda_{1,2} = 1, 0$$

← alg. mult. 1  
← alg. mult. 2

To find EVs :-  $\vec{x}_1 = \text{Ker}(A - 1I_3)$

$$= \text{Ker} \begin{pmatrix} 0 & 1 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \vec{0}$$

$$\Rightarrow \begin{pmatrix} x_2 \\ x_3 \\ 0 \end{pmatrix} = \vec{0}$$

$\Rightarrow x_2, x_3 = 0$   
 and  $x_1 = 1$  (actually any arbitrary const.)

Likewise  $\vec{x}_2 = \text{sp} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$

By inspection  $\vec{x}_1$  &  $\vec{x}_2$  span only the  $x_1$ - $x_2$  plane

$\text{rref}(A) = \text{Ker} \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} = \text{sp} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$

$\therefore$  We cannot find

$\swarrow$  S to diagonalize A!

b/c we are able to find only 2 indep. EVs!

## Geometric multiplicity of ev

$$\text{gemu}(\lambda) = \dim(\text{Ker}(A - \lambda \mathbb{I}_n))$$

$$= \text{nullity}(A - \lambda \mathbb{I}_n)$$

$$= n - \text{rank}(A - \lambda \mathbb{I}_n)$$

In prev. example

$$\text{gemu}(1) = \dim(\text{Ker}(A - \mathbb{I}_3)) = \dim \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$= 1$$

$$\neq \text{almu}(1) \\ = 2.$$

## \* Spectral th<sup>m</sup>

A matrix  $A$  is orthogonally diagonalizable ( $D = Q^{-1}A Q \equiv Q^T A Q$ )  
iff  $A$  is symmetric ( $A^T = A$ )

## \* Spectral decomposition

Let  $A$  be a real symmetric  $n \times n$  matrix  
w/ EVs  $\lambda_1, \lambda_2, \dots, \lambda_n$  and corresponding  
orthonormal EVs  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ ; then

$$A = \underbrace{\begin{pmatrix} | & | & & | \\ \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_n \\ | & | & & | \end{pmatrix}}_Q \underbrace{\begin{pmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \\ & & & \lambda_n \end{pmatrix}}_D \underbrace{\begin{pmatrix} \leftarrow \vec{v}_1 \rightarrow \\ \leftarrow \vec{v}_2 \rightarrow \\ \vdots \\ \leftarrow \vec{v}_n \rightarrow \end{pmatrix}}_{Q^T}$$

$A = Q D Q^T$

this concludes the life  
and theory of a Matrix  
in FM 112