

# LU decomposition (Gauss Elim" in disguise)

$$\text{Solving } A\vec{x} = \vec{b}$$

Let us say we are able to factorize  $A \equiv LU$  (when (Gauss Elim") row-reduction can be performed w/o row-interchange)

$$\text{s.t. } L = \begin{pmatrix} 1 & 0 & \dots & 0 \\ m_{21} & 1 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ m_{n1} & m_{n2} & \dots & m_{n,n-1} & 1 \end{pmatrix} \leftarrow \text{Lower } \Delta \text{ matrix}$$

$$U = \begin{pmatrix} a_{11}^{(1)} & a_{12}^{(1)} & \dots & a_{1n}^{(1)} \\ 0 & a_{22}^{(2)} & \dots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & a_{nn}^{(n)} \end{pmatrix} \leftarrow \text{Upper } \Delta \text{ matrix}$$

this matrix is  $\text{ref}(A)$

$$\begin{aligned} \text{1st solve } LU\vec{x} &= \vec{b} \\ \Rightarrow L\vec{y} &= \vec{b} \quad (I) \end{aligned}$$

$$\text{then solve } U\vec{x} = \vec{y} \quad (II)$$

final soln :-  $\vec{x}$

We will observe the mechanics of this w/ the help of an example.

(ii) Solve

$$\begin{aligned} x_1 + x_2 + 0x_3 + 3x_4 &= 4 \\ 2x_1 + x_2 - x_3 + x_4 &= 1 \\ 3x_1 - x_2 - x_3 + 2x_4 &= -3 \\ -x_1 + 2x_2 + 3x_3 - x_4 &= 4 \end{aligned}$$

It can be easily verified that  $A = LU$

We will reduce A to ref!

$$A = \begin{pmatrix} 1 & 1 & 0 & 3 \\ 2 & 1 & -1 & 1 \\ 3 & -1 & -1 & 2 \\ -1 & 2 & 3 & -1 \end{pmatrix}$$

Factorize A (not  $\tilde{A}$ !)

$$\downarrow R_2 - 2R_1 \rightarrow R_2$$

$$= \begin{pmatrix} 1 & 1 & 0 & 3 \\ 0 & -1 & -1 & -5 \\ 3 & -1 & -1 & 2 \\ -1 & 2 & 3 & -1 \end{pmatrix}$$

$$\downarrow R_3 - 3R_1 \rightarrow R_3$$

$$= \begin{pmatrix} 1 & 1 & 0 & 3 \\ 0 & -1 & -1 & -5 \\ 0 & -4 & -1 & -14 \\ -1 & 2 & 3 & -1 \end{pmatrix}$$

$$\downarrow R_4 - (-1)R_1 \rightarrow R_4$$

$$= \begin{pmatrix} 1 & 1 & 0 & 3 \\ 0 & -1 & -1 & -5 \\ 0 & -4 & -1 & -14 \\ 0 & 3 & 3 & 2 \end{pmatrix}$$

$$\downarrow R_3 - 4R_2 \rightarrow R_3$$

$$= \begin{pmatrix} 1 & 1 & 0 & 3 \\ 0 & -1 & -1 & -5 \\ 0 & 0 & 3 & 13 \\ 0 & 0 & 3 & 2 \end{pmatrix}$$

$$R_4 - (-3)R_2 \rightarrow R_4$$

$$\begin{pmatrix} 1 & 1 & 0 & 3 \\ 0 & -1 & -1 & -5 \\ 0 & 0 & 3 & 13 \\ 0 & 0 & 0 & -13 \end{pmatrix}$$

b/c  $R_4 - (0)R_3 \rightarrow R_4$  to obtain ref.

Some texts regard the ref where the leading non-zero entry (pivot) = 1, other texts don't → here we will require the ref in which the pivots need not be 1.

Here, read off entries of U from the ref(A)

$$U = \begin{pmatrix} 1 & 1 & 0 & 3 \\ 0 & -1 & -1 & -5 \\ 0 & 0 & 3 & 13 \\ 0 & 0 & 0 & -13 \end{pmatrix}$$

read off entries of L multipliers by considering the circles of the successive row-transformations

$$L = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Annotations:  $m_{21}$  (1),  $m_{31}$  (3),  $m_{41}$  (-1),  $m_{32}$  (4),  $m_{42}$  (-3),  $m_{43}$  (0)

Let us first solve  $L\vec{y} = \vec{b}$  — (1)

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 2 & 1 & 0 & 0 \\ 3 & 4 & 1 & 0 \\ -1 & -3 & 0 & 1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix} = \begin{pmatrix} 4 \\ 1 \\ -3 \\ 4 \end{pmatrix}$$

fwd sub.

$$\Rightarrow y_1 = 4 \quad \text{--- (i)}$$

$$2y_1 + y_2 = 1 \Rightarrow y_2 = 1 - 2 \times 4 \\ y_2 = -7 \quad \text{--- (ii)}$$

$$3y_1 + 4y_2 + y_3 = -3$$

$$\Rightarrow 12 - 28 + y_3 = -3$$

$$\Rightarrow y_3 = -3 + 16 = 13$$

$$\Rightarrow y_3 = 13 \quad \text{--- (iii)}$$

$$-y_1 - 3y_2 + y_4 = 4$$

$$\Rightarrow -4 + 21 + y_4 = 4$$

$$\Rightarrow y_4 = -13 \quad \text{--- (iv)}$$

! If you verify!  
Sub in original eqns.

Now solve.

$$U\vec{x} = \vec{y} \quad \text{--- (II)}$$

$$\Rightarrow \begin{pmatrix} 1 & 1 & 0 & 3 \\ 0 & -1 & -1 & -5 \\ 0 & 0 & 3 & 13 \\ 0 & 0 & 0 & -13 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 4 \\ -7 \\ 13 \\ -13 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 0 & - \\ & & & \\ & & & \\ & & & \end{pmatrix}$$

bkd sub.

$$x_4 = 1 \quad \text{--- (I)}$$

$$3x_3 + 13x_4 = 13$$

$$\Rightarrow x_3 = 0 \quad \text{--- (II)}$$

$$-x_2 - 5x_4 = -7$$

$$\Rightarrow x_2 = -5 + 7 = 2 \quad \text{--- (III)}$$

$$x_1 + x_2 + 3x_4 = 4 \\ \Rightarrow x_1 + 2 + 3 = 4 \\ \Rightarrow x_1 = -1 \quad \text{--- (IV)}$$

Q2) this is Q2 from last lecture.

$$\begin{aligned}x_1 + 4x_2 + 2x_3 &= -2 \\ -2x_1 - 8x_2 + 3x_3 &= 32 \\ x_2 + x_3 &= 1\end{aligned}$$

$$A = \begin{pmatrix} 1 & 4 & 2 \\ -2 & -8 & 3 \\ 0 & 1 & 1 \end{pmatrix}$$

$$\downarrow R_2 - (-2)R_1 \rightarrow R_2$$

$$\begin{pmatrix} 1 & 4 & 2 \\ 0 & 0 & 7 \\ 0 & 1 & 1 \end{pmatrix}$$

Clearly it will not be possible to perform row-reduction w/o row swapping; so let's try to solve the equivalent Eqs.

$$\begin{aligned}x_1 + 4x_2 + 2x_3 &= -2 \\ x_2 + x_3 &= 1 \\ -2x_1 - 8x_2 + 3x_3 &= 32\end{aligned}$$

$$A = \begin{pmatrix} 1 & 4 & 2 \\ 0 & 1 & 1 \\ -2 & -8 & 3 \end{pmatrix}$$

\* No transf<sup>n</sup> was req'd for  $R_2$   
 $\therefore m_{21} = 0$

$$\downarrow R_3 - (-2)R_1 \rightarrow R_3$$

$$U = \begin{pmatrix} 1 & 4 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 7 \end{pmatrix} \quad m_{31} = -2$$

$$L = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -2 & 0 & 1 \end{pmatrix} \quad \text{Indeed } A = LU$$

1st solve  $L\vec{y} = \vec{b}$  — (i)

$$\Rightarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -2 & 0 & 1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \\ 32 \end{pmatrix}$$

find sub  $\Rightarrow y_1 = -2$   
 $y_2 = 1$

$$-2y_1 + y_3 = 32$$

$$\Rightarrow y_3 = 32 + 2 \times (-2) \\ = 28$$

then solve

$$L\vec{x} = \vec{y} \text{ — (ii)}$$

$$\Rightarrow \begin{pmatrix} 1 & 4 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 7 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \\ 28 \end{pmatrix}$$

find sub  $\Rightarrow 7x_3 = 28 \Rightarrow x_3 = 4$   
 $x_2 + x_3 = 1 \Rightarrow x_2 = -3$

$$x_1 + 4x_2 + 2x_3 = -2$$

$$\Rightarrow x_1 + (-12) + 8 = -2$$

$$\Rightarrow x_1 = 2$$

$$\therefore \vec{x} = \begin{pmatrix} 2 \\ -3 \\ 4 \end{pmatrix}$$

this is exactly  
the answer we  
had obtained!

(1) In LU decomposition computational complexity reduces from  $O(n^3/3)$  to  $O(2n^2)$   
Gauss-Elim<sup>n</sup>

(2) Uniqueness & existence

Generally speaking, the LU decomp<sup>n</sup> is not unique (& may not exist)

If  $A$  is symmetric & +ve def (Hermitian)  
then  $U = (L^T)^* \equiv L^*$

& we have  $A = LL^*$  known as  
the Cholesky decomp<sup>n</sup>  
(always exist & unique)