

Experiment:4

Solving systems using Direct methods

1. Row-Reduced Echelon Form

Create a code in MATLAB that can be called as a function (name it *r_r_e.f.m*) that gives row reduced echelon form of any given vector and also its rank. Find the rref of A and B using the above mentioned function:

$$A = \begin{bmatrix} 1 & 3 & 4 \\ 5 & -9 & -8 \\ 4 & 7 & 8 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 & 6 & 7 \\ -1 & -5 & 1 \\ 1 & 9 & 0 \end{bmatrix}$$

Algorithm

// Input: $m \times n$ matrix A

// Output: $m \times n$ matrix in reduced row echelon form and rank of matrix

- (a) Create a function which take the matrix A as input
- (b) Set $i = 1, j = 1, \text{rank} = 0$
- (c) While $i \leq m$ and $j \leq n$ (m =number of rows and n =number of columns)
- (d) Find position of maximum absolute value(Pivot element and position) from $A(i, j), i \geq j$.
- (e) If pivot is equal to zero(or less than some tolerance value)
 - i. Set $j = j + 1$
else
 - ii. Perform $R_i \longleftrightarrow R_{\text{pivot}}$
 - iii. Divide each element of row i by a_{ij} , thus making the pivot a_{ij} equal to one
 - iv. For each row k from 1 to m , with $k \neq i$ subtract row i multiplied by a_{kj} from row k .
 - v. Set $i = i + 1, j = j + 1, \text{rank} = \text{rank} + 1$;
end if
end while
- (f) Return transformed matrix A and rank.

2. Solving system using Gauss-Elimination method

Create a code in MATLAB that can be called as a function (name it *Gauss.El.m*) that;

- (a) gives the solution of a system of linear equation $Ax = b$ using Gauss-elimination method, where A is a matrix of order $m \times n$, x is the array of n unknowns and

b is a m -array, check whether the solution of the system $Ax = b$ is inconsistent, infinitely many or unique solution and, compute the solution in the case of unique solution.

(b) call this function in MATLAB to solve for following:

$$A = \begin{bmatrix} 1 & -1 & 1 & -1 \\ 2 & 1 & 1 & 1 \\ 7 & -2 & -1 & -1 \end{bmatrix}, b = \begin{bmatrix} -2 \\ 5 \\ 5 \end{bmatrix} \text{ and } A = \begin{bmatrix} 0 & 2 & 4 & 1 \\ 2 & 0 & 5 & 0 \\ 1 & 0 & 1 & 2 \\ 1 & 1 & 3 & 1 \end{bmatrix}, b = \begin{bmatrix} 4 \\ 3 \\ 2 \\ 1 \end{bmatrix}$$

Algorithm

// Input: $m \times n$ matrix A and $m \times 1$ matrix b
 // Output: $n \times 1$ matrix x such that $Ax = b$

- (a) Create a function which take the matrix A and b as input.
- (b) Call the *r_e_f* function (discussed earlier in the class) for the matrix A and get the rank of matrix A .
- (c) Call the *r_e_f* function for the augmented matrix $[A \mid b]$ and get the ref form and rank.
- (d) Assign first n columns of the augmented matrix to a new matrix C and its last column to a new column vector d (to get equivalent system $Cx = d$).
- (e) If ranks of A and $[A \mid b]$ are not equal:
 - i. return *Inconsistent Solution - No Solution*
- (f) If ranks are equal and rank of A is less than number of unknowns:
 - i. return *Consistent Solution - Infinitely Many Solutions*
- (g) Otherwise, there will be a unique solution:
 - i. define solution vector as $n \times 1$ vector
 - ii. apply back substitution method and assign the values in solution vector.
 - A. get the value of last variable.
 - B. get the value of second last variable by substituting the value of last variable.
 - C. continue this till you get the value of first variable.
 - iii. return the solution vector.

3. Solving system using Gauss-Jordan-Elimination

Create a code in MATLAB that can be called as a function (name it *Gauss_Jord.m*) that;

- (a) gives the solution of a system of linear equation $Ax = b$ using Gauss-Jordan Elimination method, where A is a matrix of order $m \times n$, x is the array of n unknowns and b is a m -array, check whether the solution of the system $Ax = b$ is inconsistent, infinitely many or unique solution and, compute the solution in the case of unique solution.
- (b) call this function in MATLAB to solve for following:

$$\text{i. } A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 1 & 12 \\ 13 & 14 & 15 & 16 \end{bmatrix} \text{ and } b = \begin{bmatrix} 7 \\ 8 \\ 9 \\ 11 \end{bmatrix}$$

$$\text{ii. } A = \begin{bmatrix} 2 & 1 & 1 & 3 \\ 2 & 2 & 0 & 3 \\ 1 & 1 & -2 & 0 \end{bmatrix} \text{ and } b = \begin{bmatrix} 10 \\ 11 \\ -1 \end{bmatrix}$$

Algorithm

// Input: $m \times n$ matrix A and $m \times 1$ matrix b
// Output: $n \times 1$ matrix x such that $Ax = b$

- (a) Create a function which take the matrix A and b as input.
- (b) Call the *r_r_e_f* function (discussed earlier in the class) for the matrix A and get the rank of matrix A .
- (c) Call the *r_r_e_f* function for the augmented matrix $[A | b]$ and get the rref form and rank.
- (d) If ranks of A and $[A | b]$ are not equal:
- i. return *Inconsistent Solution - No Solution*
- (e) If ranks are equal and rank of A is less than number of unknowns:
- i. return *Consistent Solution - Infinitely Many Solutions*
- (f) Otherwise, there will be a unique solution:
- i. return the last column of rref of the augmented matrix.