

Gauss Elimination for solving systems of linear eqs.

We are solving:

Procedure:

- (I) Find an eqn. in which x_1 appears and, if necessary, interchange this eqn. w/ the 1st eqn. Thus we can assume that x_1 appears in eqn. 1.
- (II) Multiply eqn. 1 by a suitable non-zero scalar in such a way as to make the coefficient of x_1 equal to 1.
- (III) Subtract suitable multiples of eqn. 1 from eqs. 2 through m in order to eliminate x_1 from these eqs.
- (IV) Inspect eqs. 2 through m and find the first eq. which involves one of the unknowns x_2, \dots, x_n , say x_{i_2} . By interchanging eqs. once again, we can suppose that x_{i_2} appears in eq. 2.

(2)

$$x_{i_1} + *x_{i_2} + \dots + *x_n = * \quad (1)$$

$$x_{i_2} + \dots + *x_n = * \quad (2)$$

$$\dots$$

$$x_{i_r} + \dots + *x_n = *$$

$$0 = *$$

$$\vdots$$

$$0 = * \quad (m)$$

(V) Multiply eq 2. by a suitable non zero scalar to make the coefficient of x_{i_2} equal to 1.

(VI) Subtract multiples of eqn. 2 from eqns. 3 through m to eliminate x_{i_2} from these eqns.

(VII) Examine eqs. 3 through m and find the first one that involves an unknown other than x_i and x_{i_2} , say x_{i_3} . Interchange eqs. so that x_{i_3} appears in eq. 3.

(3)

this elimination procedure continues in this manner producing the so called pivotal unknowns $x_1 = x_{i_1}, x_{i_2}, \dots, x_{i_r}$ until we reach a linear system in which no further unknowns occur in the eqs. beyond the r^{th} eq.

A linear system of this sort is said to be in echelon form

the i_j are integers which satisfy

$$1 = i_1 < i_2 < \dots < i_r \leq n$$

After arriving at Echelon form, use back-substitution to solve for the unknowns x_1, x_2, \dots, x_n .

(Q) What can be said about the solution(s) of the linear system by inspecting the Echelon form? (4)

Ans) Theorem:

- (i) A linear system is consistent if and only if all the entries on the right-hand sides of those eqs. in echelon form which contain no unknowns are zero.
- (ii) If the system is consistent, the non-pivotal unknowns can be given arbitrary values; the general solution is then obtained by using back substitution to solve for the pivotal unknowns.
- (iii) the system has a unique soln. if and only if all the unknowns are pivotal.
- there exists at least one solution!*

Matrix form of Gauss Elimination.

(E)

The elementary row operations to a matrix equivalent to the operations we performed while implementing Gauss elimination to the linear system are as follows :-

(i) $R_i \leftrightarrow R_j$

(ii) $R_i : R_i + c R_j$

(iii) $R_i : c R_i$

The matrix in row-echelon form will have a descending staircase structure →

c is scalar const.

$$\left(\begin{array}{cccc|cccccc} 0 & \dots & 0 & 1 & * & \dots & * & \dots & * \\ 0 & \dots & 0 & 0 & 0 & \dots & 0 & 1 & * \\ 0 & \dots & 0 & - & - & \dots & 0 & 0 & 1 & * \\ 0 & \dots & 0 & - & - & \dots & 0 & 0 & 0 & 1 & * \\ 0 & \dots & 0 & - & - & \dots & 0 & - & - & 0 & * \\ 0 & \dots & 0 & - & - & \dots & - & 0 & - & - & 0 & * \\ 0 & \dots & 0 & - & - & \dots & - & - & 0 & - & - & 0 & * \\ 0 & \dots & 0 & - & - & \dots & - & - & - & 0 & - & * \end{array} \right)$$

(6)

eg. of matrix in row-echelon form.

$$\begin{pmatrix} 1 & 3 & 3 & 2 & 1 \\ 2 & 6 & 9 & 5 & 5 \\ -1 & -3 & 3 & 0 & 5 \end{pmatrix}$$

$$R_2: R_2 - 2R_1 \text{ and } R_3: R_3 + R_1$$

$$\begin{pmatrix} 1 & 3 & 3 & 2 & 1 \\ 0 & 0 & 3 & 1 & 3 \\ 0 & 0 & 6 & 2 & 6 \end{pmatrix}$$

$$R_2: \frac{1}{3}R_2 \text{ and } R_3: R_3 - 6R_2$$

$$\begin{pmatrix} 1 & 3 & 3 & 2 & 1 \\ 0 & 0 & 1 & \frac{1}{3} & 1 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

This matrix is in
row-echelon form!

(7)

Consider Q3 (or case 3) from prev. lecture
i.e. Lec. set 2.9

$$x_1 + 3x_2 + 3x_3 + 2x_4 = 1$$

$$2x_1 + 6x_2 + 9x_3 + 5x_4 = 5$$

$$-x_1 - 3x_2 + 3x_3 = 5$$

can be written as

$$AX = B$$

the augmented matrix is

$$M = [A|B] = \left(\begin{array}{cccc|c} 1 & 3 & 3 & 2 & 1 \\ 2 & 6 & 9 & 5 & 5 \\ -1 & -3 & 3 & 0 & 5 \end{array} \right)$$

In row-echelon form this becomes

$$\left(\begin{array}{cccc|c} 1 & 3 & 2 & 1 & 1 \\ 0 & 0 & 1 & \frac{1}{3} & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

non-pivotal entries!

0 (i.e. $0=0$)

b/c this is

this system is

give them
arbitrary
values
 $x_4 = c, x_2 = d$

$$= \begin{cases} x_1 + 3x_2 + 3x_3 + 2x_4 = 1 \\ x_3 + \frac{1}{3}x_4 = 1 \\ 0 = 0 \end{cases}$$

(B)
the pivotal entries x_1 and x_3 can be found by back substitution

$$x_1 = -2 - c - 3d$$

$$x_3 = 1 - \frac{c}{3}$$

Reading Assignment ! Gauss Elimination Algorithm .

→ refer pg. 350 - 351 of textbook by Burden & Faires (8th edn.)

→ also refer wikipedia page on Gauss Elimination

→ also refer lab manual of this course !