

5. Definition (Reduced row-echelon form or rref):

A matrix is said to be in rref if it satisfies all the following conditions:

- i. If a row has non-zero entries, then the first non-zero entry is a 1, known as the *leading 1* (or *pivot*) in this row.
- ii. If a column has a leading 1, then all the other entries in that columns are 0.
- iii. If a row contains a leading 1, then each row above it contains a leading 1 further to the left.

The third condition implies that that row of 0's, if any, appear at the bottom of the matrix.

6. Types of elementary row operations (in order to obtain the rref):

- i. Divide a row by a non-zero scalar.
- ii. Subtract a multiple of a row from another row.
- iii. Swap two rows.

We will later see that points 5 and 6 above will form the meat of a power technique known as the Gauss-Jordan elimination to solve systems of linear equations.

7. **Definition (Linear transformations):**

A function $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is called a *linear transformation* if $\exists A \in \mathbb{M}_{m \times n}(\mathbb{R})$ such that $T(\mathbf{x}) = \mathbf{Ax}$, $\forall \mathbf{x} \in \mathbb{R}^n$.

eg. The rotation matrix $\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$ is a linear transformation which rotates a vector in \mathbb{R}^2 by θ .

Ques: Given $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$, how do we find A ?

Ans: $A = \begin{pmatrix} | & | & & | \\ T(\mathbf{e}_1) & T(\mathbf{e}_2) & \cdot & T(\mathbf{e}_n) \\ | & | & & | \end{pmatrix}$ where \mathbf{e}_i is the i^{th} standard basis element of \mathbb{R}^n .

A square matrix is *invertible* if its linear transformation is invertible.

Theorem: A $n \times n$ matrix A is invertible $\iff rref(A) = I_n \equiv rank(A) = n$.

Finding inverse of a matrix: $A \in \mathbb{M}_{n \times n}(\mathbb{R})$. In order to find A^{-1} , form the augmented matrix $\tilde{A} = (A \mid I_n)$ and compute $rref(\tilde{A})$.

- If $rref(\tilde{A})$ is of the form $(I_n \mid B)$, then $A^{-1} = B$.
- If $rref(\tilde{A})$ is of another form, then A is not invertible.

$$(AB)^{-1} = B^{-1}A^{-1}.$$