

Agenda items

3/1/2022

Module 2
Lec. Set 2

→ Eigenvalues (eVs) and
Eigenvectors (EVs) of
a matrix

→ Meaning of eVs and EVs

→ Diagonalizable matrices & Similarity
transformations

→ Analytical (pen-paper) method of
finding eVs.

→ Computational method of finding
eVs. of a matrix (power method, etc)

Defⁿ (eVs and EVs) : \circ may be \mathbb{R} or \mathbb{C}

Let $A \in M_{n \times n}(\mathbb{F})$

\vec{x} is an EV of A if

$\vec{x} \in \mathbb{F}^n$ $A \vec{x} = \lambda \vec{x}$ Constant (either \mathbb{R} or \mathbb{C})

cannot be $\vec{0}$!

λ is an ev of A associated w/ the EV \vec{x} !

Meaning of the eq. $A\vec{x} = \lambda\vec{x}$

(i) Algebraic meaning

$A\vec{x} = \lambda\vec{x}$ can also be written as

$$(A - \lambda I)\vec{x} = \vec{0}$$

recall we had left out 0 from the defⁿ of EV!

i.e. the $(EV \vec{x} + \vec{0})$ form the null sp. of the matrix $(A - \lambda I)$

this is a subspace of $(A - \lambda I)$ that has a spl. name "EIGENSPACE" of λ w.r.t. A !

why?

$$\lambda \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$\lambda\vec{x}$ $\lambda I\vec{x}$

in search of meaning of $A\vec{x} = \lambda\vec{x} \dots$

Consider an example

$$A = \begin{pmatrix} 2 & -1 \\ 2 & 4 \end{pmatrix}$$

$$(A - \lambda I) = \begin{pmatrix} 2-\lambda & -1 \\ 2 & 4-\lambda \end{pmatrix}$$

Solving $A\vec{x} = \lambda\vec{x}$ is equivalent to solving the system of linear eqs.

$$\begin{pmatrix} 2-\lambda & -1 \\ 2 & 4-\lambda \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{cases} (2-\lambda)x_1 - x_2 = 0 \\ 2x_1 + (4-\lambda)x_2 = 0 \end{cases}$$

b/c EV
can NOT be
0!

When does this system of linear eqns. have a non-trivial soln.??

Ans:-

$$\text{Ker}(A - \lambda I) \neq \{ \vec{0} \}$$

characteristic eqn.

this is true only if

$(A - \lambda I)$ is non-invertible

i.e. $\det(A - \lambda I) \equiv |A - \lambda I| = 0$

i.e. $\begin{vmatrix} 2-\lambda & -1 \\ 2 & 4-\lambda \end{vmatrix} = 0 \Rightarrow \begin{cases} \lambda_1 = 3+i \\ \lambda_2 = 3-i \end{cases}$

EV w.r.t. λ_1 : $x_1 = k(-1+i)/2$
Some arb. const. $x_2 = k$

Various features of an invertible matrix

$$B \in M_{n \times n}$$

- 1) B is invertible
- 2) $B\vec{x} = \vec{b}$ has a unique soln. $\vec{x} \forall \vec{b} \in \mathbb{R}^n$
- 3) $\text{rref}(B) = I_n$
- 4) $\text{rank}(B) = n$
- 5) $\text{im}(B) = \mathbb{R}^n$
- 6) $\text{Ker}(B) = \{ \vec{0} \}$

all the above statements are equivalent

A slight digression - - -

Q) Why $\text{null}(B) = \{0\} \iff B$ is ~~not~~ invertible?

Ans) $T: U \rightarrow V$ is invertible if and only if T is one to one & onto

by inspecting im & ker of T

$\Rightarrow \dim(U) = \dim(V)$
Rank nullity thm :- $\text{null}(T) + \underbrace{\text{rank}(T)}_{\dim(V)} = \dim(U)$

$\{0\}$

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HW/exercise problem

Q) Consider $A = \begin{pmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 0 \end{pmatrix}$

i) Find the characteristic polynomial.

ii) Find the EVs of A .

iii) Find the EVs of A .

Ans :- EVs : $-1, 2, 3$
EVs : $\begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$

ii) Geometrical meaning of
 $A\vec{x} = \lambda\vec{x}$

when λ is real . . .

$A\vec{x}$ is \parallel to \vec{x}

i.e. the "EV" \vec{x} either gets stretched or compressed longitudinally when acted upon by the matrix A .

Coming Soon!

- * Diagonalizable matrices
- * Similarity transformation
- * Application of $e^{A t}$ & EVs in solutions to ODEs