

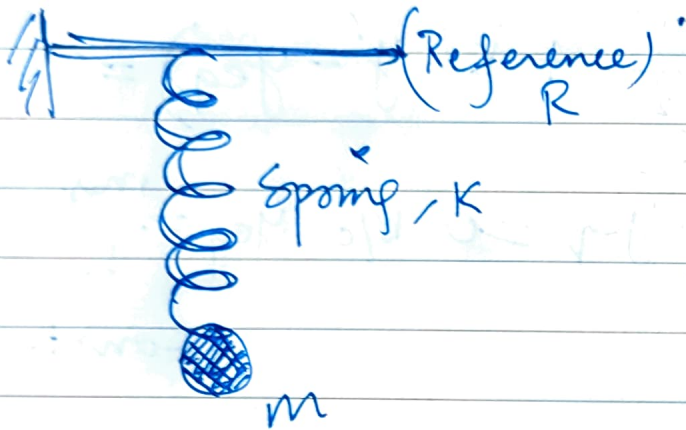
Q) Why do we study $A\vec{q} = \vec{b}$?

Simple

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lec-1: Spring-mass system



$F_{net} = mg - Ky$; y is displ. of mass

At eq^m, $F_{net} = 0 \Rightarrow y_{eq} = \frac{mg}{K}$ — (1)

Now, pull the mass down further by y so that total elongation of spring is $(y + y_{eq})$

$$F_{net} = mg - K(y + y_{eq})$$

$$m \frac{d^2 y}{dt^2} = mg - Ky - mg \quad (\text{b/c of eq(1)})$$

$$m \frac{d^2 y}{dt^2} + Ky = 0 \quad \text{--- (2) this is the model for displacement of mass from eqⁿ posⁿ!}$$

If we want to write an eqⁿ for displacement of mass w.r.t. the reference rod, R ; change variables

$$y' = y + y_{eq} \quad \text{--- (3)}$$

$$\text{or } y = y' - y_{eq}$$

$$\text{from eq (2): } m \frac{d^2 y'}{dt^2} + k(y' - y_{eq}) = 0$$

$$\text{b/c } \frac{d^2}{dt^2} y_{eq} = 0 \quad \text{b/c } y_{eq} = \frac{mg}{k}$$

= const.

$$m \frac{d^2 y'}{dt^2} + k y' = k y_{eq} = k \frac{mg}{k}$$

$$\text{or } m \frac{d^2 y'}{dt^2} + k y' = mg$$

$$\text{or } \frac{d^2 y'}{dt^2} + \omega^2 y' = g \quad \text{--- (4)}$$

$$\text{where } \omega^2 = \frac{k}{m}$$

Now that we have derived the model; I can just relabel y' as x ; so,

$$\frac{d^2 x}{dt^2} + \omega^2 x = g \quad \text{--- (4)}$$

Let's now write eq (4) in matrix-vector form: DATE / /

$$\vec{z} = \begin{pmatrix} x \\ \frac{dx}{dt} \end{pmatrix} = \begin{pmatrix} x \\ v \end{pmatrix}$$

So eq (4) \equiv the following:

$$\frac{d\vec{z}}{dt} = \begin{pmatrix} 0 & 1 \\ -\omega^2 & 0 \end{pmatrix} \vec{z} + \begin{pmatrix} 0 \\ g \end{pmatrix} \quad \text{--- (5)}$$

$$\frac{d\vec{z}}{dt} = A\vec{z} + \vec{b}_g$$

for steady state response of the spring-mass system,

demand $\frac{d\vec{z}}{dt} = 0$

i.e. $A\vec{z} = \vec{b}$ --- (6)

where $\vec{b} = -\vec{b}_g$

this is how the

linear-sys. $A\vec{z} = \vec{b}$ emerges in a simple-spring mass system.

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* Soln \vec{q} w/ oscillatory modes exist if A^{-1} exists.

* A is invertible if

$$\det(A) = \omega^2 \neq 0.$$

(True whenever $k \neq 0$
or $m \neq 0$)

* eigenvalue λ of $A = i\omega$.

\Rightarrow if $\omega = 0 \Rightarrow \lambda(A) = 0$

$\Rightarrow A$ is NOT invertible

\Rightarrow No oscillatory solns!

* Check out the python simulations & animations available on the course website

In the next lecture, we will

Study a linear chain of 10-spring mass system!

